

## Quotation and order form parallel indexer (1)

Company \_\_\_\_\_  
 Administrator \_\_\_\_\_  
 Telephone/Fax \_\_\_\_\_

E-Mail address \_\_\_\_\_  
 Project/Order no. \_\_\_\_\_  
 Date \_\_\_\_\_

### Applications

- Belt or chain conveyor       Pivot arm  
 Rotation of parts           Other (please include drawing)

#### Belt or chain conveyor

Gear ratio (if applicable)  $i=$  \_\_\_\_\_  
 Feed length \_\_\_\_\_ Distance of deflexion pulleys \_\_\_\_\_  
 Number of work piece carriers \_\_\_\_\_

#### Deflexion pulleys

Quantity \_\_\_\_\_  $\varnothing$  \_\_\_\_\_ Thickness \_\_\_\_\_  
 Material or weight \_\_\_\_\_

#### Belt / Chain

Weight \_\_\_\_\_ Friction coefficient \_\_\_\_\_  
 Work piece carrier weight \_\_\_\_\_

#### Work piece

Quantity \_\_\_\_\_ Weight \_\_\_\_\_

#### Pivot arm

Pivot angle \_\_\_\_\_ Number of arms \_\_\_\_\_  
 Distance from pivot point to centre of mass of acceptance \_\_\_\_\_  
 Weight of one arm \_\_\_\_\_  
 Weight of fixture and work piece \_\_\_\_\_

#### Rotation of parts

Rotation angle \_\_\_\_\_ Weight of fixture and work piece \_\_\_\_\_

Stepping operation (cycle time fixed, resting time variable)

Continuous motion (cycle and resting time fixed)

Desired index time [s]  $t_s=$  \_\_\_\_\_

Desired dwell time [s] (continuous motion only) \_\_\_\_\_

Number of indexes [1/min] \_\_\_\_\_

Required lifetime (cycle time only, typically 12,000 h) \_\_\_\_\_

Additional forces and loads (please describe)

\_\_\_\_\_  
 \_\_\_\_\_  
 \_\_\_\_\_

### Scheibenkurven-Schrittgetriebe

Type  XP  TP

Frame Size \_\_\_\_\_

Number of Stops  $n=$  \_\_\_\_\_

Switching angle  $\alpha=$  \_\_\_\_\_

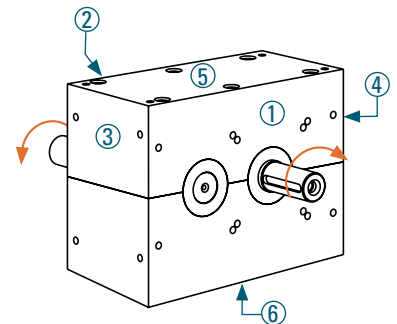
Mounting side of nameplate (Standard 3) \_\_\_\_\_

Standard Input shaft  yes  no

If no, deviations \_\_\_\_\_ mm

Standard output shaft  yes  no

If no, deviations \_\_\_\_\_ mm

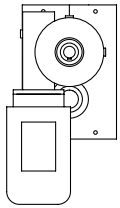


Mounting side of nameplate / Direction of rotation of input and output shaft

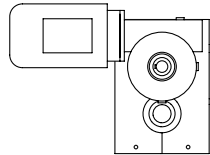
## Quotation and order form parallel indexer (2)

### Possible mounting positions for the drive units

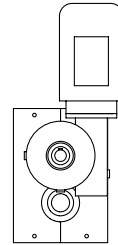
SL-0



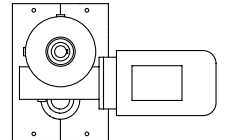
SL-90



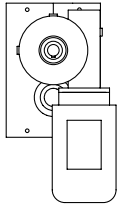
SL-180



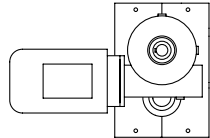
SL-270



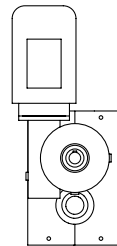
SR-0



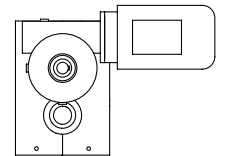
SR-90



SR-180



SR-270



### Drive

with Drive

without drive

Mounting Position (see above) \_\_\_\_\_

Terminal Box Position (see right) \_\_\_\_\_

Voltage Motor

230/400-50 Hz

different Voltage \_\_\_\_\_

Voltage Brake

24V DC

different Voltage \_\_\_\_\_

Manual release on brake  Yes  No

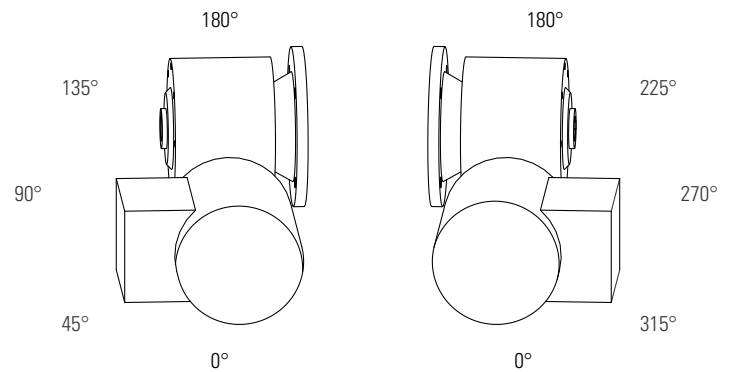
Motor Handwheel  Yes  No

Input Safety Clutch  Yes  No

Additional specifications (temperature sensor, connector assembly, brand..)

\_\_\_\_\_

### Terminal Box Position



### Universal Controller TIC

Universal Controller TIC  Yes  No